

Package ‘mlr3viz’

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Title Visualizations for 'mlr3'

Version 0.9.0

Description Visualization package of the 'mlr3' ecosystem. It features plots for mlr3 objects such as tasks, learners, predictions, benchmark results, tuning instances and filters via the 'autoplot()' generic of 'ggplot2'. The package draws plots with the 'viridis' color palette and applies the minimal theme. Visualizations include barplots, boxplots, histograms, ROC curves, and Precision-Recall curves.

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URL <https://mlr3viz.mlr-org.com>, <https://github.com/mlr-org/mlr3viz>

BugReports <https://github.com/mlr-org/mlr3viz/issues>

Depends R (>= 3.1.0)

Imports checkmate, data.table, ggplot2 (>= 3.3.0), mlr3misc (>= 0.7.0), scales, utils, viridis

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'LearnerClassifCVGlmnet.R' 'LearnerClassifGlmnet.R'
'LearnerClassifRpart.R' 'LearnerClustHierarchical.R'
'LearnerRegr.R' 'LearnerRegrCVGlmnet.R' 'LearnerRegrGlmnet.R'
'LearnerRegrRpart.R' 'OptimInstanceBatchSingleCrit.R'
'Prediction.R' 'PredictionClassif.R' 'PredictionClust.R'

'PredictionRegr.R' 'ResampleResult.R' 'Task.R' 'TaskClassif.R'
 'TaskClust.R' 'TaskRegr.R' 'TuningInstanceBatchSingleCrit.R'
 'EnsembleFSResult.R' 'as_precrec.R' 'bibentries.R' 'helper.R'
 'plot_learner_prediction.R' 'reexports.R' 'zzz.R'

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mlr3viz-package

mlr3viz: Visualizations for 'mlr3'

Description

Visualization package of the 'mlr3' ecosystem. It features plots for mlr3 objects such as tasks, learners, predictions, benchmark results, tuning instances and filters via the 'autoplot()' generic of 'ggplot2'. The package draws plots with the 'viridis' color palette and applies the minimal theme. Visualizations include barplots, boxplots, histograms, ROC curves, and Precision-Recall curves.

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See Also

Useful links:

- <https://mlr3viz.mlr-org.com>
- <https://github.com/mlr-org/mlr3viz>
- Report bugs at <https://github.com/mlr-org/mlr3viz/issues>

as_precrec

Convert to 'precrec' Format

Description

Converts to a format which is understood by `precrec::evalmod()` of package **precrec**.

Usage

```
as_precrec(object)

## S3 method for class 'PredictionClassif'
as_precrec(object)

## S3 method for class 'ResampleResult'
as_precrec(object)

## S3 method for class 'BenchmarkResult'
as_precrec(object)
```

Arguments

object (any)
Object to convert.

Value

Object as created by `precrec::mmdata()`.

References

Saito T, Rehmsmeier M (2017). "Precrec: fast and accurate precision-recall and ROC curve calculations in R." *Bioinformatics*, **33**(1), 145-147. doi:10.1093/bioinformatics/btw570.

autoplot.BenchmarkResult

Plots for Benchmark Results

Description

Visualizations for `mlr3::BenchmarkResult`. The argument type controls what kind of plot is drawn. Possible choices are:

- "boxplot" (default): Boxplots of performance measures, one box per `mlr3::Learner` and one facet per `mlr3::Task`.
- "roc": ROC curve (1 - specificity on x, sensitivity on y). The `mlr3::BenchmarkResult` may only have a single `mlr3::Task` and a single `mlr3::Resampling`. Note that you can subset any `mlr3::BenchmarkResult` with its `$filter()` method (see examples). Requires package `precrec`.
- "prc": Precision recall curve. See "roc".

Usage

```
## S3 method for class 'BenchmarkResult'
autoplot(
  object,
  type = "boxplot",
  measure = NULL,
  theme = theme_minimal(),
  ...
)
```

Arguments

object	(mlr3::BenchmarkResult).
type	(character(1)): Type of the plot. See description.
measure	(mlr3::Measure) Performance measure to use.
theme	(ggplot2::theme()) The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
...	(ignored).

Value

`ggplot2::ggplot()`.

References

Saito T, Rehmsmeier M (2017). "Precrec: fast and accurate precision-recall and ROC curve calculations in R." *Bioinformatics*, **33**(1), 145-147. doi:10.1093/bioinformatics/btw570.

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)

  tasks = tsks(c("pima", "sonar"))
  learner = lrns(c("classif.featureless", "classif.rpart"),
    predict_type = "prob")
  resampling = rsmps("cv")
  object = benchmark(benchmark_grid(tasks, learner, resampling))

  head(fortify(object))
  autoplot(object)
  autoplot(object$clone(deep = TRUE)$filter(task_ids = "pima"), type = "roc")
}
```

 autoplot.EnsembleFSResult

Plots for Ensemble Feature Selection Results

Description

Visualizations for [EnsembleFSResult](#). The argument type determines the type of plot generated. The available options are:

- "pareto" (default): Scatterplot of performance versus the number of features, possibly including the **Pareto front**, which allows users to decide how much performance they are willing to trade off for a more sparse model.
- "performance": Boxplot of performance across the different learners used in the ensemble feature selection process. Each box represents the distribution of scores across different resampling iterations for a particular learner.
- "n_features": Boxplot of the number of features selected by each learner in the different resampling iterations.
- "stability": Barplot of stability score for each learner used in the ensemble feature selection. This plot shows how similar are the output feature sets from each learner across the different resamplings.

Usage

```
## S3 method for class 'EnsembleFSResult'
autoplot(
  object,
  type = "pareto",
  pareto_front = "stepwise",
  stability_measure = "jaccard",
  stability_args = NULL,
  theme = theme_minimal(),
  ...
)
```

Arguments

object	(mlr3fselect::EnsembleFSResult).
type	(character(1)): Type of the plot. See description.
pareto_front	(character(1)) Type of pareto front to plot. Can be "stepwise" (default), "estimated" or "none".
stability_measure	(character(1)) The stability measure to be used in case type = "stability". One of the measures returned by stability::listStabilityMeasures() in lower case. Default is "jaccard".

`stability_args` (list) Additional arguments passed to the stability measure function.
`theme` (`ggplot2::theme()`) The `ggplot2::theme_minimal()` is applied by default to all plots.
`...` (ignored).

Value

`ggplot2::ggplot()`.

Examples

```

if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3fselect)

  set.seed(42)
  efsr = ensemble_fselect(
    fselector = fs("random_search"),
    task = tsk("sonar"),
    learners = lrns(c("classif.rpart", "classif.featureless")),
    init_resampling = rsmpl("subsampling", repeats = 5),
    inner_resampling = rsmpl("cv", folds = 3),
    measure = msr("classif.ce"),
    terminator = trm("evals", n_evals = 5)
  )

  # Pareto front (default, stepwise)
  autoplot(efsr)

  # Pareto front (estimated)
  autoplot(efsr, pareto_front = "estimated")

  # Performance
  autoplot(efsr, type = "performance")

  # Number of features
  autoplot(efsr, type = "n_features")

  # stability
  autoplot(efsr, type = "stability")
}

```

Description

Visualizations for `mlr3filters::Filter`. The argument type controls what kind of plot is drawn. Possible choices are:

- "barplot" (default): Bar plot of filter scores.

Usage

```
## S3 method for class 'Filter'
autoplot(object, type = "boxplot", n = Inf, theme = theme_minimal(), ...)
```

Arguments

object	(<code>mlr3filters::Filter</code>).
type	(character(1)): Type of the plot. See description.
n	(integer(1)) Only include the first n features with the highest importance. Defaults to all features.
theme	(<code>ggplot2::theme()</code>) The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
...	(ignored).

Value

`ggplot2::ggplot()`.

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)
  library(mlr3filters)

  task = tsk("mtcars")
  f = flt("correlation")
  f$calculate(task)

  head(fortify(f))
  autoplot(f, n = 5)
}
```

`autoplot.LearnerClassif`*Plot for Classification Learners*

Description

Visualizations for `mlr3::LearnerClassif`. The argument `type` controls what kind of plot is drawn. Possible choices are:

- "prediction" (default): Decision boundary of the learner and the true class labels.

Usage

```
## S3 method for class 'LearnerClassif'
autoplot(
  object,
  type = "prediction",
  task,
  grid_points = 100L,
  expand_range = 0,
  theme = theme_minimal(),
  ...
)
```

Arguments

<code>object</code>	<code>(mlr3::LearnerClassif)</code> .
<code>type</code>	<code>(character(1))</code> : Type of the plot. See description.
<code>task</code>	<code>(mlr3::Task)</code> Train task.
<code>grid_points</code>	<code>(integer(1))</code> Number of grid points per feature dimension.
<code>expand_range</code>	<code>(numeric(1))</code> Expand the range of the grid.
<code>theme</code>	<code>(ggplot2::theme())</code> The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
<code>...</code>	<code>(ignored)</code> .

Value

`ggplot2::ggplot()`.

Examples

```

if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)

  task = tsk("pima")$select(c("age", "pedigree"))
  learner = lrn("classif.rpart", predict_type = "prob")
  learner$train(task)

  autoplot(learner, type = "prediction", task)
}

```

```

autoplot.LearnerClassifCVGlmnet
Plots for GLMNet Learners

```

Description

Visualizations for [mlr3learners:LearnerClassifGlmnet](#). The argument `type` controls what kind of plot is drawn. Possible choices are:

- "prediction" (default): Decision boundary of the learner and the true class labels.
- "ggfortify": Visualizes the model using the package [ggfortify](#).

Usage

```

## S3 method for class 'LearnerClassifCVGlmnet'
autoplot(
  object,
  type = "prediction",
  task = NULL,
  grid_points = 100L,
  expand_range = 0,
  theme = theme_minimal(),
  ...
)

## S3 method for class 'LearnerClassifGlmnet'
autoplot(
  object,
  type = "prediction",
  task = NULL,
  grid_points = 100L,
  expand_range = 0,
  theme = theme_minimal(),
  ...
)

```

```

)

## S3 method for class 'LearnerRegrCVGlmnet'
autoplot(
  object,
  type = "prediction",
  task = NULL,
  grid_points = 100L,
  expand_range = 0,
  theme = theme_minimal(),
  ...
)

## S3 method for class 'LearnerRegrGlmnet'
autoplot(
  object,
  type = "prediction",
  task = NULL,
  grid_points = 100L,
  expand_range = 0,
  theme = theme_minimal(),
  ...
)

```

Arguments

object	(mlr3learners::LearnerClassifGlmnet mlr3learners::LearnerRegrGlmnet mlr3learners::LearnerRegrCVGlmnet mlr3learners::LearnerRegrCVGlmnet).
type	(character(1)): Type of the plot. See description.
task	(mlr3::Task) Train task.
grid_points	(integer(1)) Number of grid points per feature dimension.
expand_range	(numeric(1)) Expand the range of the grid.
theme	(ggplot2::theme()) The ggplot2::theme_minimal() is applied by default to all plots.
...	(ignored).

Value

[ggplot2::ggplot\(\)](#).

References

Tang Y, Horikoshi M, Li W (2016). “ggfortify: Unified Interface to Visualize Statistical Result of Popular R Packages.” *The R Journal*, **8**(2), 474–485. doi:[10.32614/RJ2016060](https://doi.org/10.32614/RJ2016060).

Examples

```
## Not run:
library(mlr3)
library(mlr3viz)
library(mlr3learners)

# classification
task = tsk("sonar")
learner = lrn("classif.glmnet")
learner$train(task)
autoplot(learner, type = "ggfortify")

# regression
task = tsk("mtcars")
learner = lrn("regr.glmnet")
learner$train(task)
autoplot(learner, type = "ggfortify")

## End(Not run)
```

```
autoplot.LearnerClassifRpart
Plots for Rpart Learners
```

Description

Visualizations for [mlr3::LearnerClassifRpart](#). The argument `type` controls what kind of plot is drawn. Possible choices are:

- "prediction" (default): Decision boundary of the learner and the true class labels.
- "ggparty": Visualizes the tree using the package [ggparty](#).

Usage

```
## S3 method for class 'LearnerClassifRpart'
autoplot(
  object,
  type = "prediction",
  task = NULL,
  grid_points = 100L,
  expand_range = 0,
  theme = theme_minimal(),
  ...
)

## S3 method for class 'LearnerRegrRpart'
autoplot(
  object,
```

```

    type = "prediction",
    task = NULL,
    grid_points = 100L,
    expand_range = 0,
    theme = theme_minimal(),
    ...
  )

```

Arguments

object	(mlr3::LearnerClassifRpart mlr3::LearnerRegrRpart).
type	(character(1)): Type of the plot. See description.
task	(mlr3::Task) Train task.
grid_points	(integer(1)) Number of grid points per feature dimension.
expand_range	(numeric(1)) Expand the range of the grid.
theme	(ggplot2::theme()) The ggplot2::theme_minimal() is applied by default to all plots.
...	(ignored).

Value

[ggplot2::ggplot\(\)](#).

Examples

```

if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)

  # classification
  task = tsk("iris")
  learner = lrn("classif.rpart", keep_model = TRUE)
  learner$train(task)
  autoplot(learner, type = "ggparty")

  # regression
  task = tsk("mtcars")
  learner = lrn("regr.rpart", keep_model = TRUE)
  learner$train(task)
  autoplot(learner, type = "ggparty")
}

```

 autoplot.LearnerClustHierarchical

Plots for Hierarchical Clustering Learners

Description

Visualizations for hierarchical clusters. The argument `type` controls what kind of plot is drawn. Possible choices are:

- "dend" (default): Dendrograms using **ggdendro** package.
- "scree": Scree plot that shows the number of possible clusters on the x-axis and the height on the y-axis.

Usage

```
## S3 method for class 'LearnerClustHierarchical'
autoplot(
  object,
  type = "dend",
  task = NULL,
  theme = theme_minimal(),
  theme_dendro = TRUE,
  ...
)
```

Arguments

<code>object</code>	(mlr3cluster::LearnerClustAgnes mlr3cluster::LearnerClustDiana mlr3cluster::LearnerClustHclust).
<code>type</code>	(character(1)): Type of the plot. See description.
<code>task</code>	(mlr3::Task) Optionally, pass the task to add labels of observations to a hclust dendrogram. Labels are set via the row names of the task.
<code>theme</code>	(ggplot2::theme()) The ggplot2::theme_minimal() is applied by default to all plots.
<code>theme_dendro</code>	(logical(1)) If TRUE (default), the special dendrogram theme from ggdendro package is used in plot "dend". Set to FALSE to use the theme passed in <code>theme</code> .
<code>...</code>	(ignored).

Value

[ggplot2::ggplot\(\)](#).

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3cluster)
  library(mlr3viz)

  task = tsk("usarrests")

  # agnes clustering
  learner = lrn("clust.agnes")
  learner$train(task)
  autoplot(learner)

  # diana clustering
  learner = lrn("clust.diana")
  learner$train(task)
  autoplot(learner)

  # hclust clustering
  learner = lrn("clust.hclust")
  learner$train(task)
  autoplot(learner, type = "scree")
}
```

autoplot.LearnerRegr *Plot for Regression Learners*

Description

Visualizations for [mlr3::LearnerRegr](#). The argument `type` controls what kind of plot is drawn. Possible choices are:

- "prediction" (default): Decision boundary of the learner and the true class labels.

Usage

```
## S3 method for class 'LearnerRegr'
autoplot(
  object,
  type = "prediction",
  task,
  grid_points = 100L,
  expand_range = 0,
  theme = theme_minimal(),
  ...
)
```

Arguments

object	(mlr3::LearnerRegr).
type	(character(1)): Type of the plot. See description.
task	(mlr3::Task) Train task.
grid_points	(integer(1)) Number of grid points per feature dimension.
expand_range	(numeric(1)) Expand the range of the grid.
theme	(ggplot2::theme()) The ggplot2::theme_minimal() is applied by default to all plots.
...	(ignored).

Value

ggplot2::ggplot().

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)

  task = tsk("mtcars")$select(c("am", "carb"))
  learner = lrn("regr.rpart")
  learner$train(task)

  autoplot(learner, type = "prediction", task)
}
```

autoplot.OptimInstanceBatchSingleCrit

Plots for Optimization Instances

Description

Visualizations for `bbotk::OptimInstanceBatchSingleCrit`. The argument `type` controls what kind of plot is drawn. Possible choices are:

- "marginal" (default): Scatter plots of x versus y. The color of the points shows the batch number.
- "performance": Scatter plots of batch number versus y
- "parameter": Scatter plots of batch number versus input. The color of the points shows the y values.

- "parallel": Parallel coordinates plot. x values are rescaled by $(x - \text{mean}(x)) / \text{sd}(x)$.
- "points": Scatter plot of two x dimensions versus. The color of the points shows the y values.
- "surface": Surface plot of two x dimensions versus y values. The y values are interpolated with the supplied [mlr3::Learner](#).
- "pairs": Plots all x and y values against each other.
- "incumbent": Plots the incumbent versus the number of configurations.

Usage

```
## S3 method for class 'OptimInstanceBatchSingleCrit'
autoplot(
  object,
  type = "marginal",
  cols_x = NULL,
  trafo = FALSE,
  learner = mlr3::lrn("regr.ranger"),
  grid_resolution = 100,
  batch = NULL,
  theme = theme_minimal(),
  ...
)
```

Arguments

object	(bbotk::OptimInstanceBatchSingleCrit).
type	(character(1)): Type of the plot. See description.
cols_x	(character()) Column names of x values. By default, all untransformed x values from the search space are plotted. Transformed hyperparameters are prefixed with <code>x_domain_</code> .
trafo	(logical(1)) If FALSE (default), the untransformed x values are plotted. If TRUE, the transformed x values are plotted.
learner	(mlr3::Learner) Regression learner used to interpolate the data of the surface plot.
grid_resolution	(numeric()) Resolution of the surface plot.
batch	(integer()) The batch number(s) to limit the plot to. The default is all batches.
theme	(ggplot2::theme()) The ggplot2::theme_minimal() is applied by default to all plots.
...	(ignored).

Value

[ggplot2::ggplot\(\)](#).

Examples

```

if (requireNamespace("mlr3") && requireNamespace("bbotk") && requireNamespace("patchwork")) {
  library(bbotk)
  library(paradox)

  fun = function(xs) {
    c(y = -(xs[[1]] - 2)^2 - (xs[[2]] + 3)^2 + 10)
  }
  domain = ps(
    x1 = p_dbl(-10, 10),
    x2 = p_dbl(-5, 5)
  )
  codomain = ps(
    y = p_dbl(tags = "maximize")
  )
  obfun = ObjectiveRFun$new(
    fun = fun,
    domain = domain,
    codomain = codomain
  )

  instance = oi(objective = obfun, terminator = trm("evals", n_evals = 20))

  optimizer = opt("random_search", batch_size = 2)
  optimizer$optimize(instance)

  # plot y versus batch number
  print(autoplot(instance, type = "performance"))

  # plot x1 values versus performance
  print(autoplot(instance, type = "marginal", cols_x = "x1"))

  # plot parallel coordinates plot
  print(autoplot(instance, type = "parallel"))

  # plot pairs
  print(autoplot(instance, type = "pairs"))

  # plot incumbent
  print(autoplot(instance, type = "incumbent"))
}

```

autoplot.PredictionClassif

Plots for Classification Predictions

Description

Visualizations for [mlr3::PredictionClassif](#). The argument type controls what kind of plot is drawn. Possible choices are:

- "stacked" (default): Stacked barplot of true and estimated class labels.
- "roc": ROC curve (1 - specificity on x, sensitivity on y). Requires package **precrec**.
- "prc": Precision recall curve. Requires package **precrec**.
- "threshold": Systematically varies the threshold of the `mlr3::PredictionClassif` object and plots the resulting performance as returned by measure.

Usage

```
## S3 method for class 'PredictionClassif'
autoplot(
  object,
  type = "stacked",
  measure = NULL,
  theme = theme_minimal(),
  ...
)
```

Arguments

object	(<code>mlr3::PredictionClassif</code>).
type	(character(1)): Type of the plot. See description.
measure	(<code>mlr3::Measure</code>) Performance measure to use.
theme	(<code>ggplot2::theme()</code>) The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
...	(ignored).

Value

`ggplot2::ggplot()`.

References

Saito T, Rehmsmeier M (2017). "Precrec: fast and accurate precision-recall and ROC curve calculations in R." *Bioinformatics*, **33**(1), 145-147. doi:10.1093/bioinformatics/btw570.

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)

  task = tsk("spam")
  learner = lrn("classif.rpart", predict_type = "prob")
  object = learner$train(task)$predict(task)

  head(fortify(object))
}
```

```

autoplot(object)
autoplot(object, type = "roc")
autoplot(object, type = "prc")
}

```

autoplot.PredictionClust

Plots for Cluster Predictions

Description

Visualizations for `mlr3cluster::PredictionClust`. The argument `type` controls what kind of plot is drawn. Possible choices are:

- "scatter" (default): scatterplot with correlation values and colored cluster assignments.
- "sil": Silhouette plot with mean silhouette value as the reference line. Requires package [ggfortify](#).
- "pca": Perform PCA on data and color code cluster assignments. Inspired by and uses [ggfortify::autoplot.kmeans](#).

Usage

```

## S3 method for class 'PredictionClust'
autoplot(
  object,
  task,
  row_ids = NULL,
  type = "scatter",
  theme = theme_minimal(),
  ...
)

```

Arguments

<code>object</code>	(<code>mlr3cluster::PredictionClust</code>).
<code>task</code>	(<code>mlr3cluster::TaskClust</code>).
<code>row_ids</code>	(<code>integer()</code>) Row ids to subset task data to ensure that only the data used to make predictions are shown in plots.
<code>type</code>	(<code>character(1)</code>): Type of the plot. See description.
<code>theme</code>	(<code>ggplot2::theme()</code>) The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
<code>...</code>	(ignored).

Value

`ggplot2::ggplot()`.

References

Tang Y, Horikoshi M, Li W (2016). “ggfortify: Unified Interface to Visualize Statistical Result of Popular R Packages.” *The R Journal*, **8**(2), 474–485. doi:10.32614/RJ2016060.

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3cluster)
  library(mlr3viz)

  task = tsk("usarrests")
  learner = lrn("clust.kmeans", centers = 3)
  object = learner$train(task)$predict(task)

  head(fortify(object))
  autoplot(object, task)
}
```

autoplot.PredictionRegr

Plots for Regression Predictions

Description

Visualizations for `mlr3::PredictionRegr`. The argument `type` controls what kind of plot is drawn. Possible choices are:

- "xy" (default): Scatterplot of "true" response vs. "predicted" response. By default a linear model is fitted via `geom_smooth(method = "lm")` to visualize the trend between x and y (by default colored blue). In addition `geom_abline()` with `slope = 1` is added to the plot. Note that `geom_smooth()` and `geom_abline()` may overlap, depending on the given data.
- "histogram": Histogram of residuals: $r = y - \hat{y}$.
- "residual": Plot of the residuals, with the response \hat{y} on the "x" and the residuals on the "y" axis. By default a linear model is fitted via `geom_smooth(method = "lm")` to visualize the trend between x and y (by default colored blue).
- "confidence": Scatterplot of "true" response vs. "predicted" response with confidence intervals. Error bars calculated as `object$reponse +/- quantile * object$se` and so only possible with `predict_type = "se"`. `geom_abline()` with `slope = 1` is added to the plot.

Usage

```
## S3 method for class 'PredictionRegr'
autoplot(
  object,
  type = "xy",
  binwidth = NULL,
  theme = theme_minimal(),
  quantile = 1.96,
  ...
)
```

Arguments

object	(mlr3::PredictionRegr).
type	(character(1)): Type of the plot. See description.
binwidth	(integer(1)) Width of the bins for the histogram.
theme	(ggplot2::theme()) The ggplot2::theme_minimal() is applied by default to all plots.
quantile	(numeric(1)) Quantile multiplier for standard errors for type="confidence". Default 1.96.
...	(ignored).

Value

[ggplot2::ggplot\(\)](#).

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)

  task = tsk("boston_housing")
  learner = lrn("regr.rpart")
  object = learner$train(task)$predict(task)

  head(fortify(object))
  autoplot(object)
  autoplot(object, type = "histogram", binwidth = 1)
  autoplot(object, type = "residual")

  if (requireNamespace("mlr3learners")) {
    library(mlr3learners)
    learner = lrn("regr.ranger", predict_type = "se")
    object = learner$train(task)$predict(task)
    autoplot(object, type = "confidence")
  }
}
```

```
}

```

```
autoplot.ResampleResult
```

Plots for Resample Results

Description

Visualizations for [mlr3::ResampleResult](#). The argument `type` controls what kind of plot is drawn. Possible choices are:

- "boxplot" (default): Boxplot of performance measures.
- "histogram": Histogram of performance measures.
- "roc": ROC curve (1 - specificity on x, sensitivity on y). The predictions of the individual [mlr3::Resamplings](#) are merged prior to calculating the ROC curve (micro averaged). Requires package [precrec](#).
- "prc": Precision recall curve. See "roc".
- "prediction": Plots the learner prediction for a grid of points. Needs models to be stored. Set `store_models = TRUE` for `[mlr3::resample]`. For classification, we support tasks with exactly two features and learners with `predict_type =` set to "response" or "prob". For regression, we support tasks with one or two features. For tasks with one feature we can print confidence bounds if the predict type of the learner was set to "se". For tasks with two features the predict type will be ignored.

Usage

```
## S3 method for class 'ResampleResult'
autoplot(
  object,
  type = "boxplot",
  measure = NULL,
  predict_sets = "test",
  binwidth = NULL,
  theme = theme_minimal(),
  ...
)
```

Arguments

<code>object</code>	(mlr3::ResampleResult).
<code>type</code>	(character(1)): Type of the plot. See description.
<code>measure</code>	(mlr3::Measure) Performance measure to use.

predict_sets	(character()) Only for type set to "prediction". Which points should be shown in the plot? Can be a subset of ("train", "test") or empty.
binwidth	(integer(1)) Width of the bins for the histogram.
theme	(ggplot2::theme()) The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
...	(ignored).

Value

`ggplot2::ggplot()`.

References

Saito T, Rehmsmeier M (2017). "Precrec: fast and accurate precision-recall and ROC curve calculations in R." *Bioinformatics*, **33**(1), 145-147. doi:10.1093/bioinformatics/btw570.

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)

  task = tsk("sonar")
  learner = lrn("classif.rpart", predict_type = "prob")
  resampling = rsmp("cv", folds = 3)
  object = resample(task, learner, resampling)

  head(fortify(object))

  # Default: boxplot
  autoplot(object)

  # Histogram
  autoplot(object, type = "histogram", bins = 30)

  # ROC curve, averaged over resampling folds:
  autoplot(object, type = "roc")

  # ROC curve of joint prediction object:
  autoplot(object$prediction(), type = "roc")

  # Precision Recall Curve
  autoplot(object, type = "prc")

  # Prediction Plot
  task = tsk("iris")$select(c("Sepal.Length", "Sepal.Width"))
  resampling = rsmp("cv", folds = 3)
  object = resample(task, learner, resampling, store_models = TRUE)
  autoplot(object, type = "prediction")
}
```



```
}

```

autoplot.TaskClassif *Plots for Classification Tasks*

Description

Visualizations for `mlr3::TaskClassif`. The argument type controls what kind of plot is drawn. Possible choices are:

- "target" (default): Bar plot of the target variable (default).
- "duo": Passes data to `GGally::ggduo()`. `columnsX` is the target and `columnsY` are the features.
- "pairs": Passes data to `GGally::ggpairs()`. Color is set to target column.

Usage

```
## S3 method for class 'TaskClassif'
autoplot(object, type = "target", theme = theme_minimal(), ...)
```

Arguments

object	(<code>mlr3::TaskClassif</code>).
type	(character(1)): Type of the plot. See description.
theme	(<code>ggplot2::theme()</code>) The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
...	(ignored).

Value

`ggplot2::ggplot()`.

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)

  task = tsk("iris")

  head(fortify(task))
  autoplot(task)
  autoplot(task$clone())$select(c("Sepal.Length", "Sepal.Width")),
  type = "pairs")
  autoplot(task, type = "duo")
}
```

autoplot.TaskClust *Plots for Clustering Tasks*

Description

Visualizations for `mlr3cluster::TaskClust`. The argument `type` controls what kind of plot is drawn. Possible choices are:

- "pairs" (default): Passes data `GGally::ggpairs()`.

Usage

```
## S3 method for class 'TaskClust'  
autoplot(object, type = "pairs", theme = theme_minimal(), ...)
```

Arguments

<code>object</code>	(<code>mlr3cluster::TaskClust</code>).
<code>type</code>	(<code>character(1)</code>): Type of the plot. See description.
<code>theme</code>	(<code>ggplot2::theme()</code>) The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
<code>...</code>	(ignored).

Value

`ggplot2::ggplot()`.

Examples

```
if (requireNamespace("mlr3")) {  
  library(mlr3)  
  library(mlr3cluster)  
  library(mlr3viz)  
  
  task = mlr_tasks$get("usarrests")  
  
  head(fortify(task))  
  autoplot(task)  
}
```

autoplot.TaskRegr *Plots for Regression Tasks*

Description

Visualizations for `mlr3::TaskRegr`. The argument type controls what kind of plot is drawn. Possible choices are:

- "target" (default): Box plot of the target variable.
- "pairs": Passes data to `GGally::ggpairs()`. Color is set to target column.

Usage

```
## S3 method for class 'TaskRegr'  
autoplot(object, type = "target", theme = theme_minimal(), ...)
```

Arguments

object	(<code>mlr3::TaskRegr</code>).
type	(character(1)): Type of the plot. See description.
theme	(<code>ggplot2::theme()</code>) The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
...	(ignored).

Value

`ggplot2::ggplot()`.

Examples

```
if (requireNamespace("mlr3")) {  
  library(mlr3)  
  library(mlr3viz)  
  
  task = tsk("mtcars")  
  task$select(c("am", "carb"))  
  
  head(fortify(task))  
  autoplot(task)  
  autoplot(task, type = "pairs")  
}
```

autoplot.TuningInstanceBatchSingleCrit
Plots for Tuning Instances

Description

Visualizations for [mlr3tuning::TuningInstanceBatchSingleCrit](#). The argument type controls what kind of plot is drawn. Possible choices are:

- "marginal" (default): Scatter plots of x versus y. The color of the points shows the batch number.
- "performance": Scatter plots of batch number versus y
- "parameter": Scatter plots of batch number versus input. The color of the points shows the y values.
- "parallel": Parallel coordinates plot. hyperparameters are rescaled by $(x - \text{mean}(x)) / \text{sd}(x)$.
- "points": Scatter plot of two x dimensions versus. The color of the points shows the y values.
- "surface": Surface plot of two x dimensions versus y values. The y values are interpolated with the supplied [mlr3::Learner](#).
- "pairs": Plots all x and y values against each other.
- "incumbent": Plots the incumbent versus the number of configurations.

Usage

```
## S3 method for class 'TuningInstanceBatchSingleCrit'
autoplot(
  object,
  type = "marginal",
  cols_x = NULL,
  trafo = FALSE,
  learner = mlr3::lrn("regr.ranger"),
  grid_resolution = 100,
  theme = theme_minimal(),
  ...
)
```

Arguments

object	(mlr3tuning::TuningInstanceBatchSingleCrit .
type	(character(1)): Type of the plot. See description.
cols_x	(character()): Column names of hyperparameters. By default, all untransformed hyperparameters are plotted. Transformed hyperparameters are prefixed with x_domain_.

trafo	(logical(1)) If FALSE (default), the untransformed hyperparameters are plotted. If TRUE, the transformed hyperparameters are plotted.
learner	(mlr3::Learner) Regression learner used to interpolate the data of the surface plot.
grid_resolution	(numeric()) Resolution of the surface plot.
theme	(ggplot2::theme()) The <code>ggplot2::theme_minimal()</code> is applied by default to all plots.
...	(ignored).

Value

`ggplot2::ggplot()`.

Examples

```

if (requireNamespace("mlr3tuning") && requireNamespace("patchwork")) {
  library(mlr3tuning)

  learner = lrn("classif.rpart")
  learner$param_set$values$cp = to_tune(0.001, 0.1)
  learner$param_set$values$minsplit = to_tune(1, 10)

  instance = ti(
    task = tsk("iris"),
    learner = learner,
    resampling = rsmpl("holdout"),
    measure = msr("classif.ce"),
    terminator = trm("evals", n_evals = 10))

  tuner = tnr("random_search")

  tuner$optimize(instance)

  # plot performance versus batch number
  autoplot(instance, type = "performance")

  # plot cp values versus performance
  autoplot(instance, type = "marginal", cols_x = "cp")

  # plot transformed parameter values versus batch number
  autoplot(instance, type = "parameter", trafo = TRUE)

  # plot parallel coordinates plot
  autoplot(instance, type = "parallel")

  # plot pairs
  autoplot(instance, type = "pairs")
}

```

 plot_learner_prediction

Plots for Learner Predictions

Description

Visualizations for the `mlr3::Prediction` of a single `mlr3::Learner` on a single `mlr3::Task`.

- For classification we support tasks with exactly two features and learners with `predict_type` set to "response" or "prob".
- For regression we support tasks with one or two features. For tasks with one feature we print confidence bounds if the `predict_type` of the learner was set to "se". For tasks with two features the `predict_type` will be ignored.

Note that this function is a wrapper around `autoplot.ResampleResult()` for a temporary `mlr3::ResampleResult` using `mlr3::mlr_resamplings_holdout` with ratio 1 (all observations in the training set).

Usage

```
plot_learner_prediction(learner, task, grid_points = 100L, expand_range = 0)
```

Arguments

<code>learner</code>	(<code>mlr3::Learner</code>).
<code>task</code>	(<code>mlr3::Task</code>).
<code>grid_points</code>	(<code>integer(1)</code>) Resolution of the grid. For factors, ordered and logicals this value is ignored.
<code>expand_range</code>	(<code>numeric(1)</code>) Expand the prediction range for numerical features.

Value

`ggplot2::ggplot()`.

Examples

```
if (requireNamespace("mlr3")) {
  library(mlr3)
  library(mlr3viz)

  task = mlr3::tsk("pima")$select(c("age", "glucose"))
  learner = lrn("classif.rpart", predict_type = "prob")
  p = plot_learner_prediction(learner, task)
  print(p)
}
```

predict_grid	<i>Generates a data.table of evenly distributed points.</i>
--------------	---

Description

For each point we have the predicted class / regression value in column response. If the learner predicts probabilities, a column ".prob.response" is added that contains the probability of the predicted class

Usage

```
predict_grid(learners, task, grid_points, expand_range)
```

Arguments

learners	list of trained learners, each learner belongs to one resampling iteration
task	the task all learners are trained on
grid_points	(int): see sequenize
expand_range	see sequenize

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